

3. (amended) Device according to Claim 2, [characterized in that] wherein connection takes place by means of a coupling element based on an electrorheological or magnetorheological fluid.

4. (amended) Device according to [Claims 2 to 3, characterized in that] Claim 1, wherein it has at least one other auxiliary mass (114), which is connected to the absorber mass (113) by means of another spring/damper element (116), which can be connected up if required.

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5. (amended) Device according to [one of Claims 1 to 4, characterized in that] Claim 1, wherein the spring/damper coupling elements are a combination of torsion, coil or gas-pressure springs with dampers based on electrorheological fluids or magnetorheological fluids.

6. (amended) Devices according to Claim 5, wherein [characterized in that] the spring elements are gas-pressure springs (81, 81', 82).

7. (amended) Hydraulic suspension system based on two or more gas-pressure springs (81, 81', 82), [characterized in that] wherein one gas-pressure spring (81) has an ERF or MRF damper element (86) and is connected to another gas-pressure spring (82) by [means of] at least one other damper or coupling element (87) based on ERF or MRF.